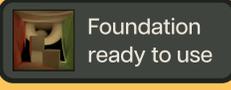


Pulse of light going through a bottle at one trillion frames per second (Camera Culture Group, MIT Media Lab)

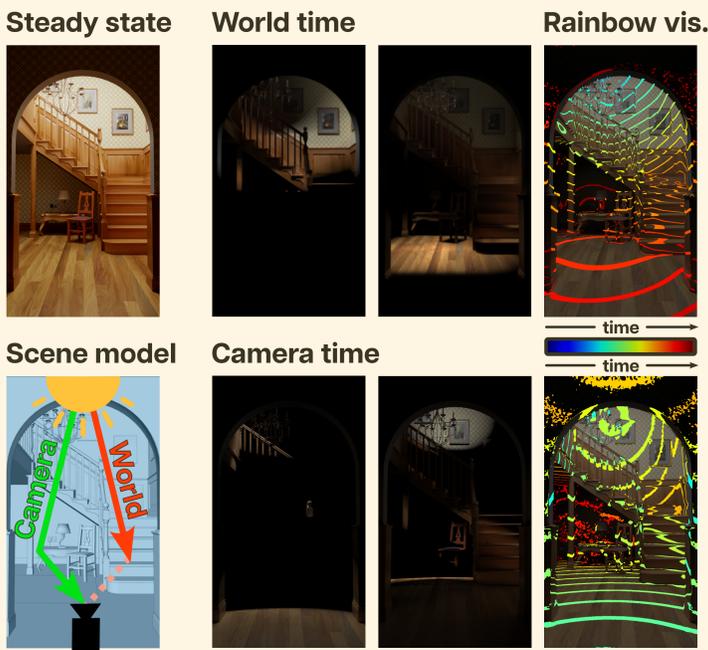
Our recreation of the bottle scene, rendered using MITRANSIENT

MITRANSIENT is a physically-based light transport tool for time-gated and time-resolved cameras, and more

| Imaging hardware | Main features | And many more! | Check it out |
|---|---|--|--|
|  Gated cameras  Transient cameras  LIDAR  AMCW |  Implemented in Mitsuba 3  Foundation ready to use  Python-only package  Support for NLOS setups | <ul style="list-style-type: none"> Spectral rendering Volumetric rendering Transient polarization Transient derivatives for inverse rendering Spatiotemporal filters Tools for NLOS setups  |  Project page Tutorials  Coca-Cola light Full video |

 github.com/diegoroyo/mitransient \$ pip install mitransient  mitransient.readthedocs.io

Example: Staircase scene



Transient derivatives
 The effect of floor reflectance on the image pixels, over time



Time-resolved estimator
 transient_path

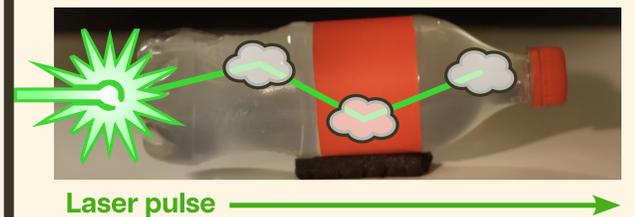
```
<integrator
type="transient_path">
<bool
name="camera_unwarp"
value="true"/>
<integer
name="max_depth"
value="15"/>
<string
name="temporal_filter"
value="gaussian"/>
</integrator>
```

Video result
 transient_hdr_film

```
<film
type="transient_hdr_film">
<integer
name="temporal_bins"
value="450"/>
<float
name="bin_width_opl"
value="0.02"/>
<float
name="start_opl"
value="0.0"/>
</film>
```

Volumetric rendering: Coca-cola light scene

Scene setup



Volumetric integrator
 transient_prbvolpath

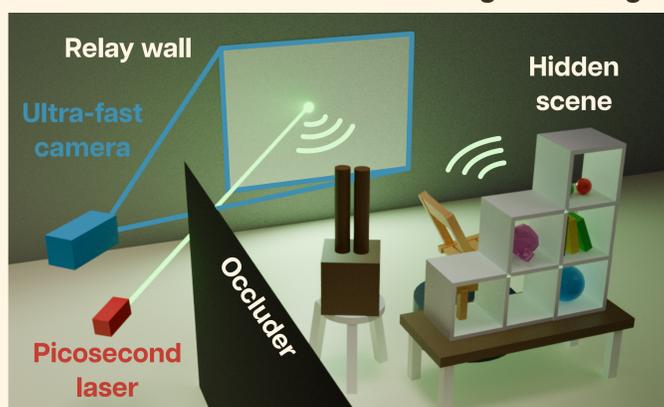
```
<integrator
type="transient_prbvolpath">
<bool
name="camera_unwarp"
value="false"/>
<string
name="temporal_filter"
value="gaussian"/>
...
</integrator>
```

Homogeneous medium
 homogeneous

```
<medium type="homogeneous">
<float name="albedo"
value="0.4"/>
<float name="sigma_t"
value="0.3"/>
<string type="hg">
<float name="g"
value="0.7"/>
</phase>
</medium>
```

Non-line-of-sight imaging: office scene

Goal: reconstruct hidden scene using indirect light



Running is easy with our tool Y-TAL

```
$ tal render office
office/office.yaml
```

```
num_bins: 3000
bin_width_opl: 0.003
start_opl: 0.0

scan_type: single
sensor_width: 180
sensor_height: 130
laser_lookat_x: 90
laser_lookat_y: 65

geometry:
- mesh: # hidden scene
  type: obj
  filename: office.obj
- mesh: # relay wall
  type: rectangle
```

Hidden scene



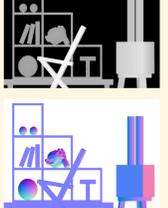
Reconstruction



Our simulation



Depth & normals



Get Y-TAL

